



DIAMOND TURNING OF TEXTURED SURFACES USING FAST TOOL SERVO SYSTEM

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Pusan National University, Korea



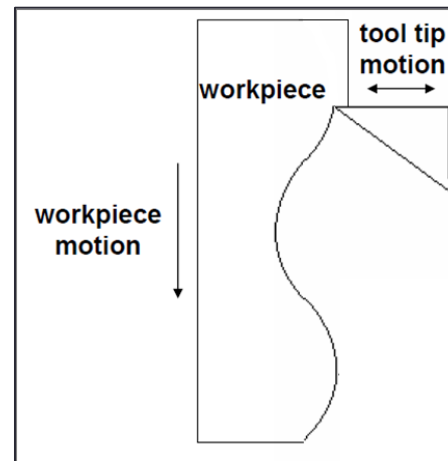
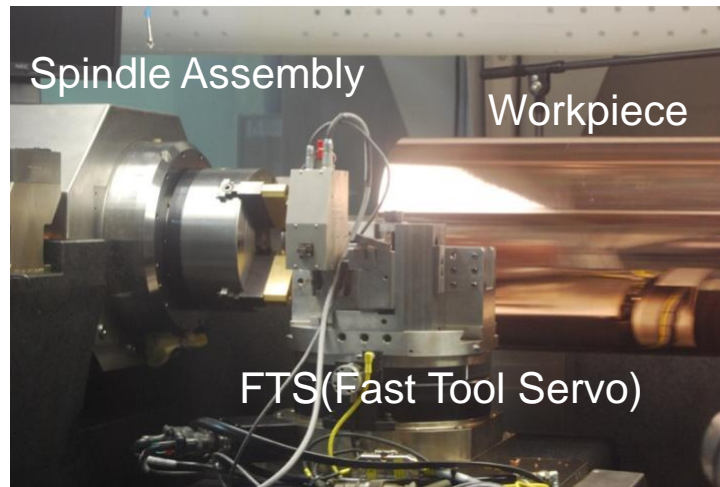
Outlines

- ❖ **Background of diamond turning using FTS**
- ❖ **Aims of this work**
- ❖ **Design and evaluation of FTS**
- ❖ **Machining test using FTS**
- ❖ **Conclusions**

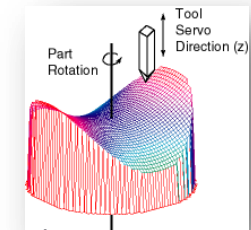
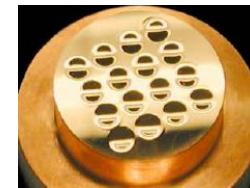
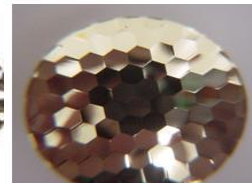
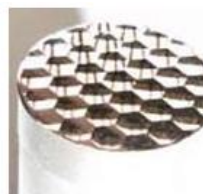
Background of diamond turning with FTS

✓ Fast Tool Servo (FTS)

- An auxiliary servo module of the tool holder with an actuator that oscillates the tool at a particular bandwidth.
- FTS System is used in a variety of the diamond turning applications.



Optical surfaces



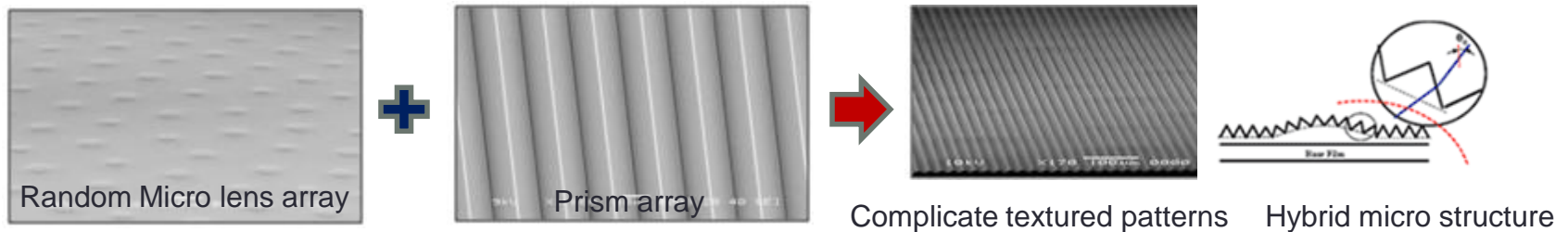
Micro lens array (ITRC)
nonrotationally symmetric surfaces

Lens (Precitech Inc.)

Background : Motivation

✓ Technological trends of micro machining using FTS

- Rising luminance of display as concentrating light through diffuser sheet vertically with light condensing function of prism and micro lens.(LMS Co., LTD)



- light condensing of micro lens => luminance up

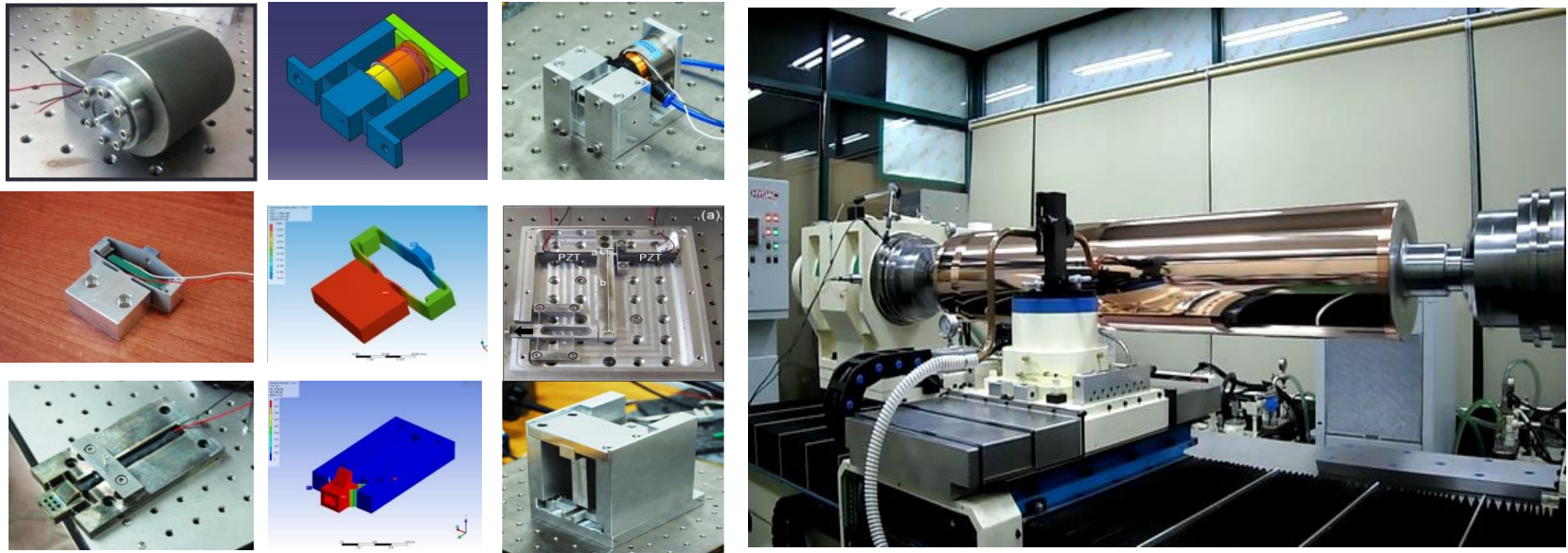
✓ Technologies ;

- How to manufacture master roll using FTS, **efficiently**.
 - High bandwidth FTS actuated with the effective stroke
- How to get high machining **accuracy**(form accuracy, surface roughness)
 - FTS errors ; hysteresis, frequency response, etc.
 - Cutting conditions ; tool design, cutting path(CAD/CAM)

Aims

Purposes of this work

- Developing FTS System for improving machining accuracy in diamond turning
 - Reducing dynamic errors of FTS(hysteresis, frequency response etc.)
- Finding machining conditions to perform high bandwidth FTS cutting

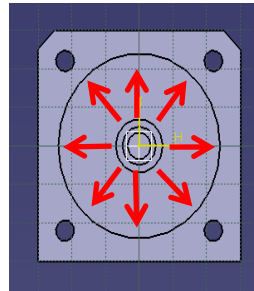
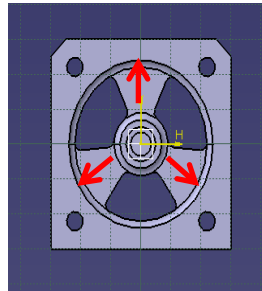
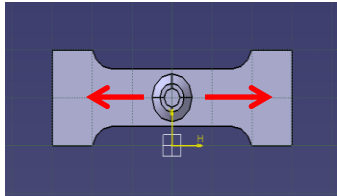


Outlines

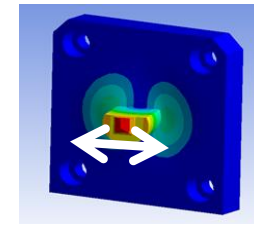
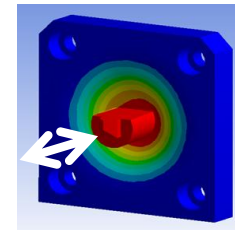
- ❖ Background of diamond turning using FTS
- ❖ Aims of this work
- ❖ **Design and evaluation of FTS**
- ❖ Machining test using FTS
- ❖ Conclusions

Developing fast tool servo(FTS) system for diamond turning

- ✓ Designing the various leaf springs of FTS actuated by PZT.
- ✓ Investigating the hysteresis and the stroke of FTS for designed models.

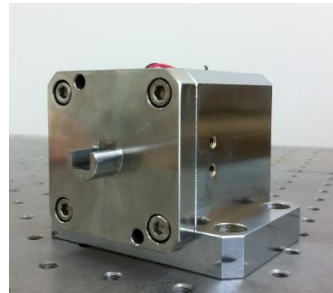
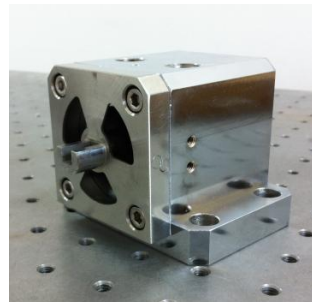
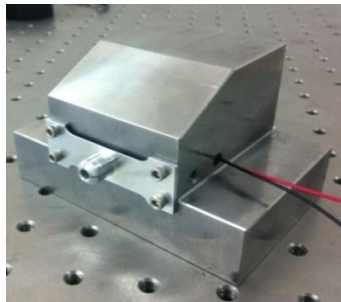


<Type A:two bridges> <Type B:three bridges> <Type C:disk >



<Mode1>

<Mode2>

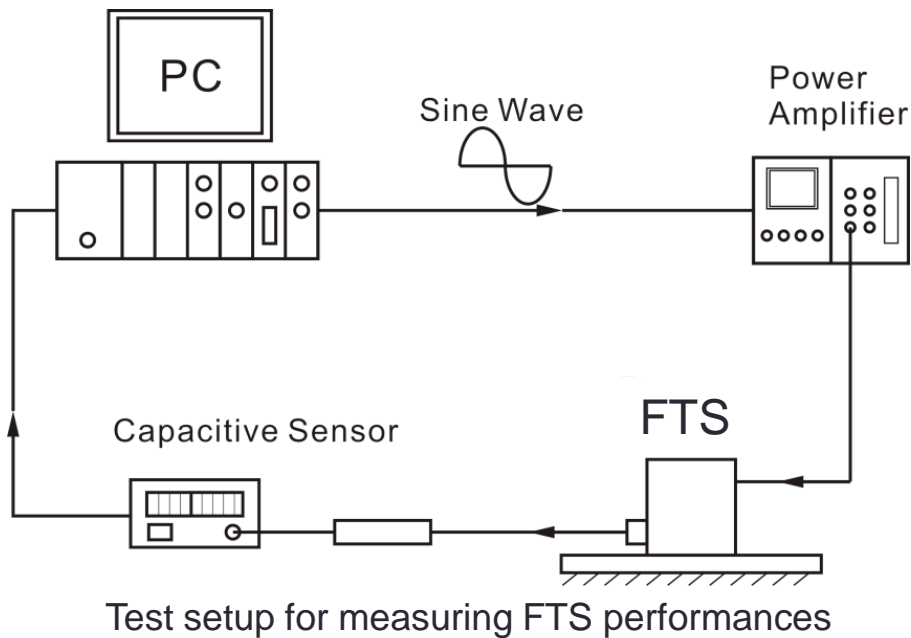


- ✓ Natural frequency : type C > type B > type A

Type	Natural Frequencies		
	A	B	C
Mode1	895Hz	1873Hz	2489Hz
Mode2	1150Hz	2615Hz	3592Hz
Mode3	2074Hz	2703Hz	3669Hz
Mode4	12179Hz	14483Hz	20033Hz

Experimental Setup for testing performances of FTS

- ✓ The waveforms which was generated in a PC with Lab VIEW S/W were amplified by power Amp. to supply to the PZT actuator.
- ✓ The corresponding displacement of FTS stroke was measured by a capacitive sensor.

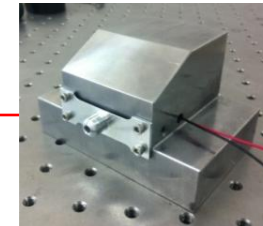
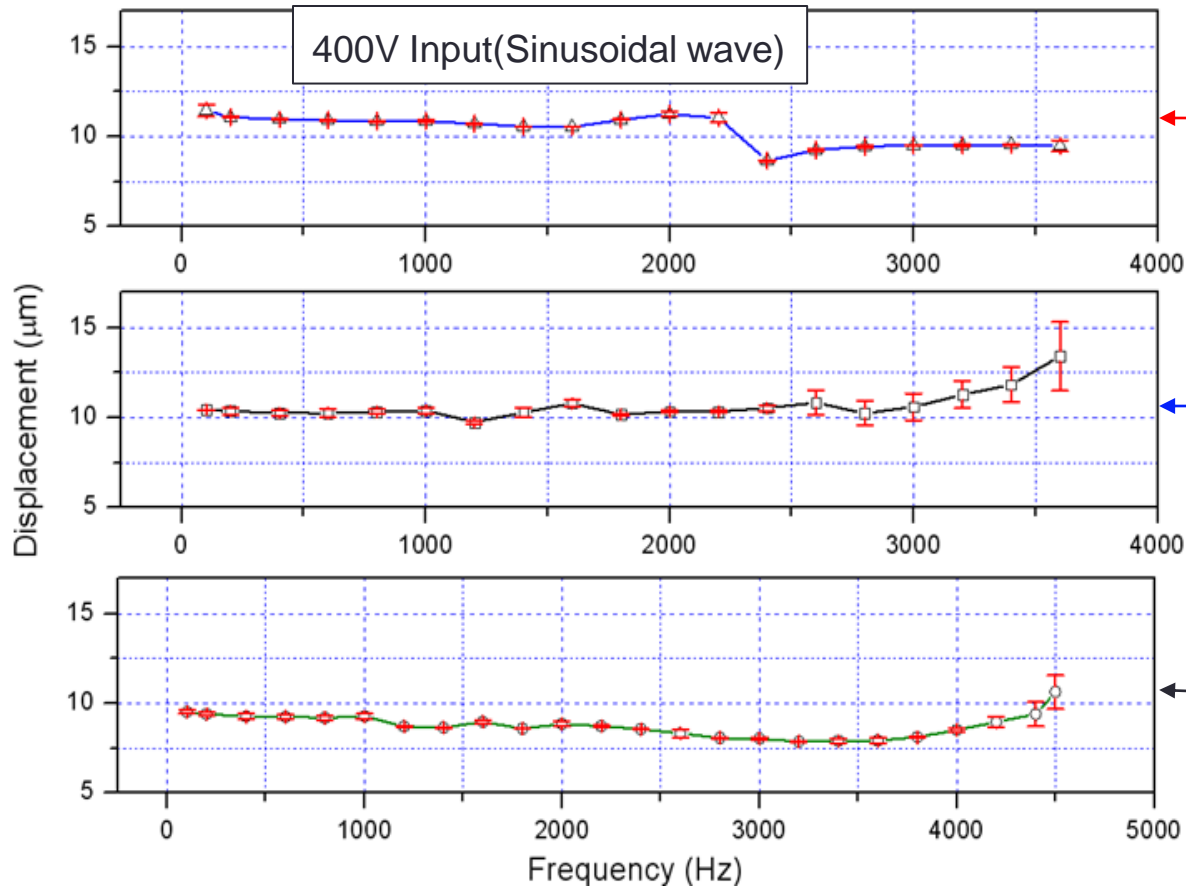


High voltage amplifier

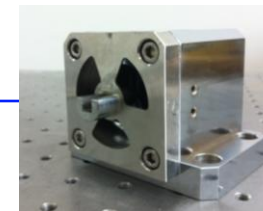
Amp - Models	E-472.20(PI)
Channels	2
Average output power	110 W
Voltage gain	100±1
Output voltage	3 to 1100 V

Peak to peak strokes according to actuating frequencies of FTS

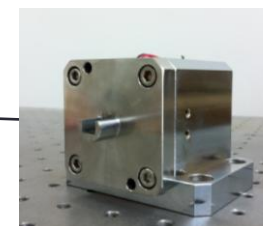
✓ Compared three types of FTS



Type A

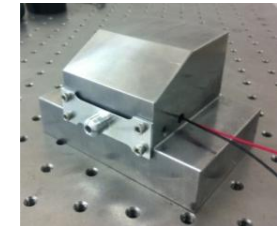
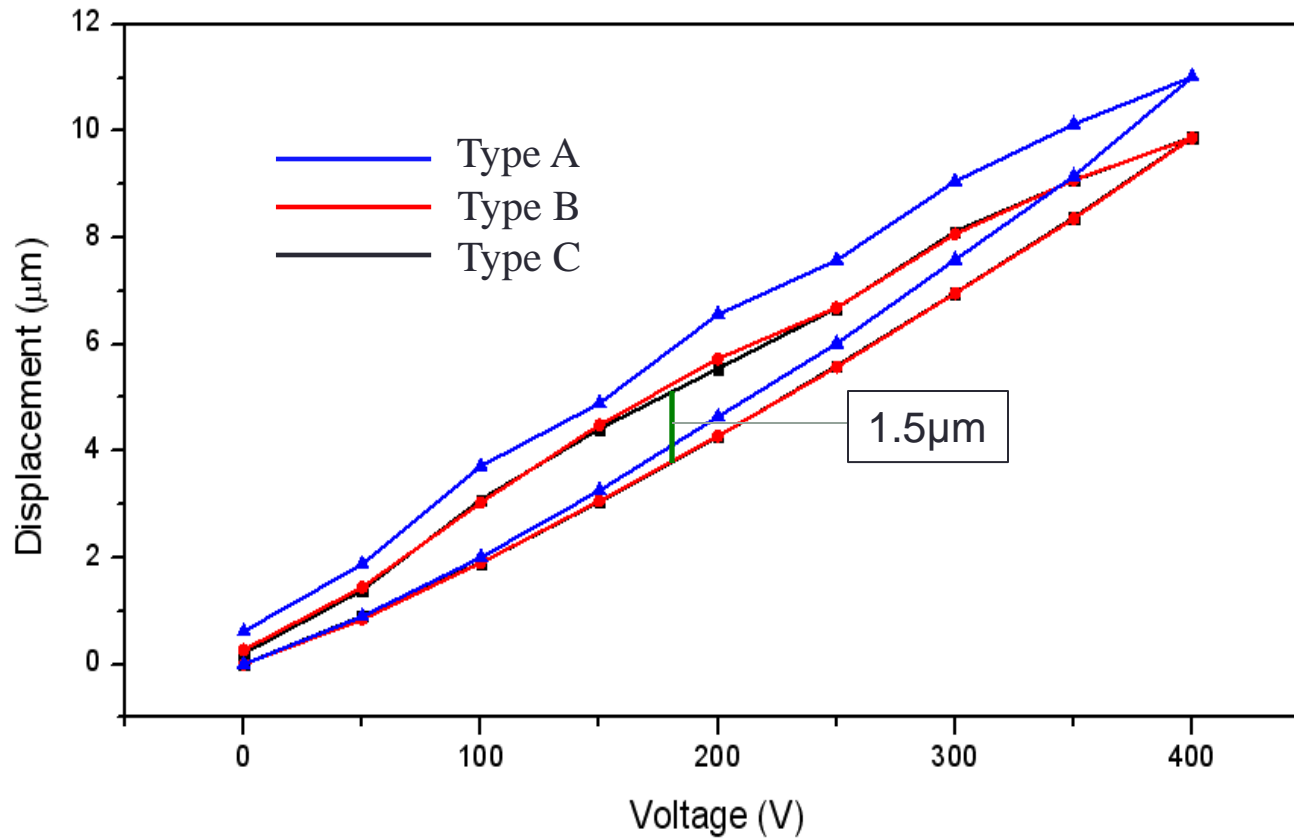


Type B

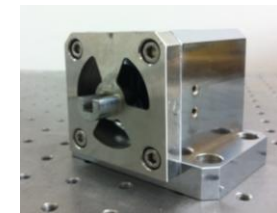


Type C

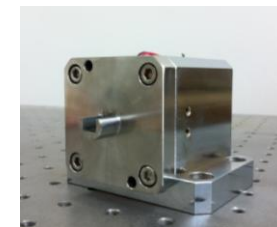
Comparing hysteresis for three types of FTS



Type A



Type B

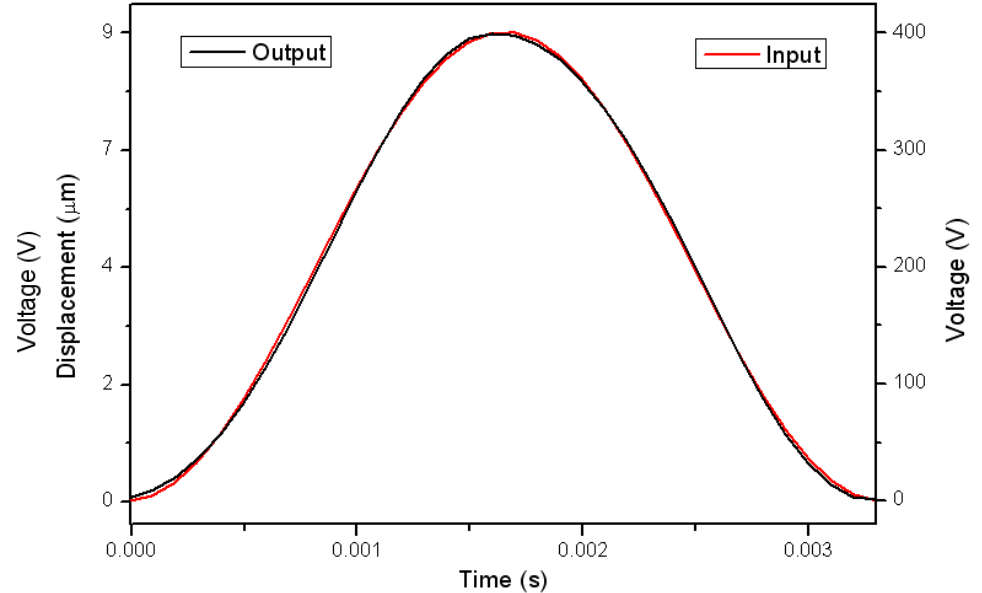
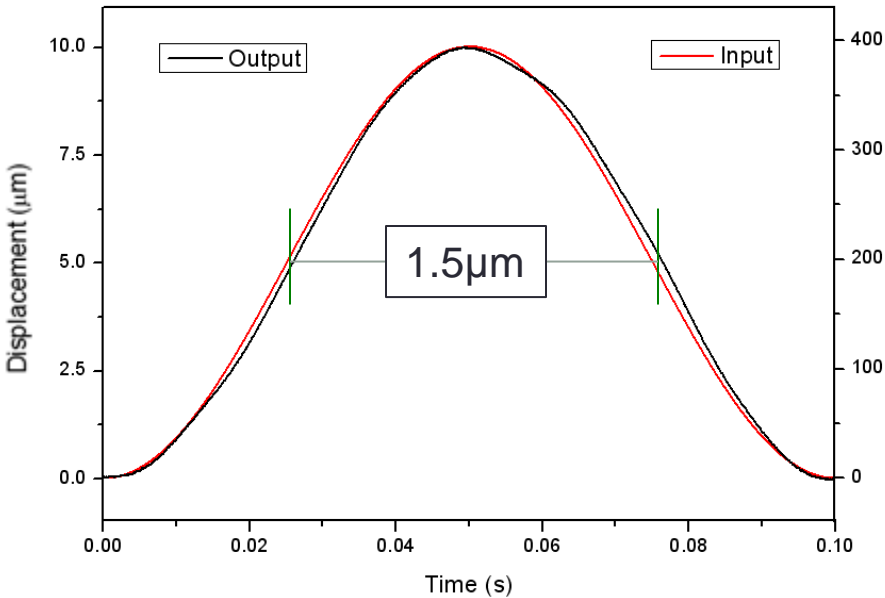


Type C

Comparison of profile errors between input and output signals of FTS(type C)

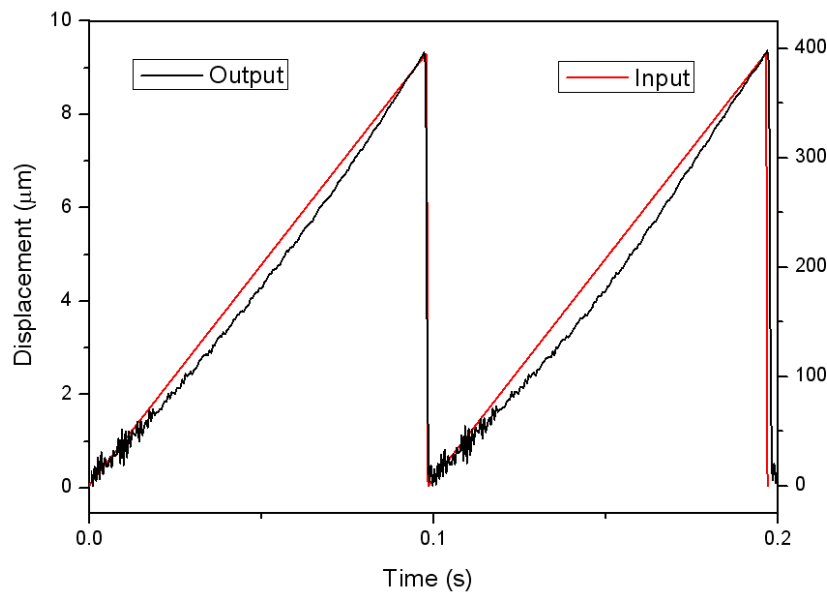
Actuating frequency : 10Hz
Input voltage : 400V(Sine wave)

Actuating frequency : 300Hz
Input voltage : 400V(Sine wave)

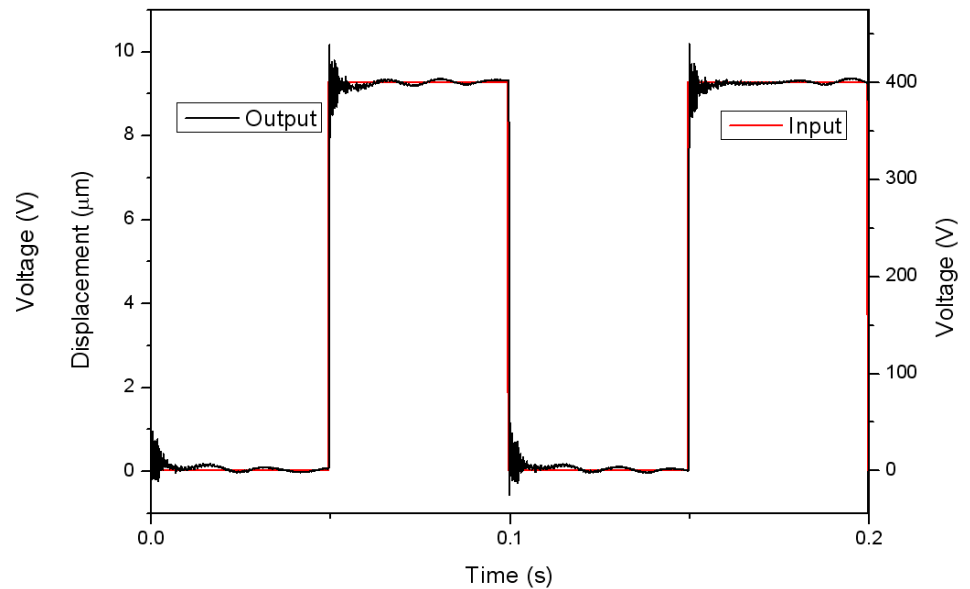


Comparison of profile errors in triangular and square wave input (type C)

Actuating frequency : 10Hz, Input voltage : 400V



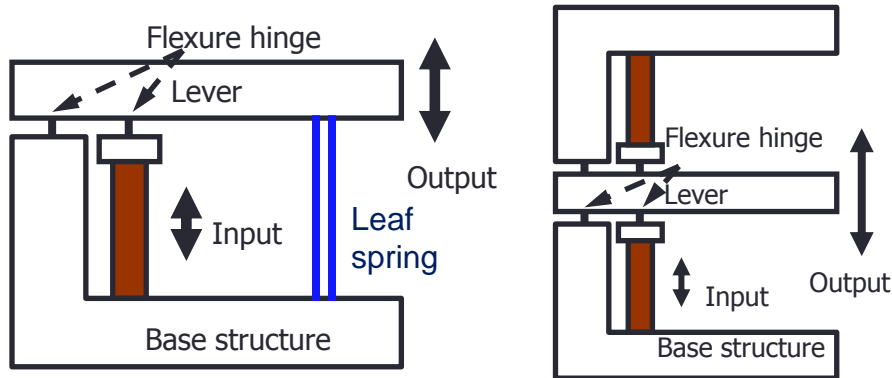
Triangular wave



square wave

Design FTS actuated by dual PZT

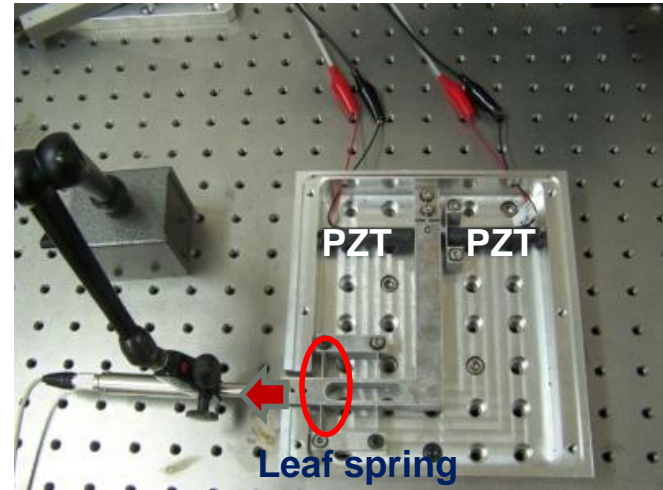
- ✓ Comparing two types of FTS actuated by single and dual PZT
- ✓ Using lever mechanism to amplify the output stroke of FTS



FTS actuated by single PZT : SFTS

FTS actuated by dual PZT : DFTS

<Schematic diagrams of two types PZT>



<Experimental Setup>

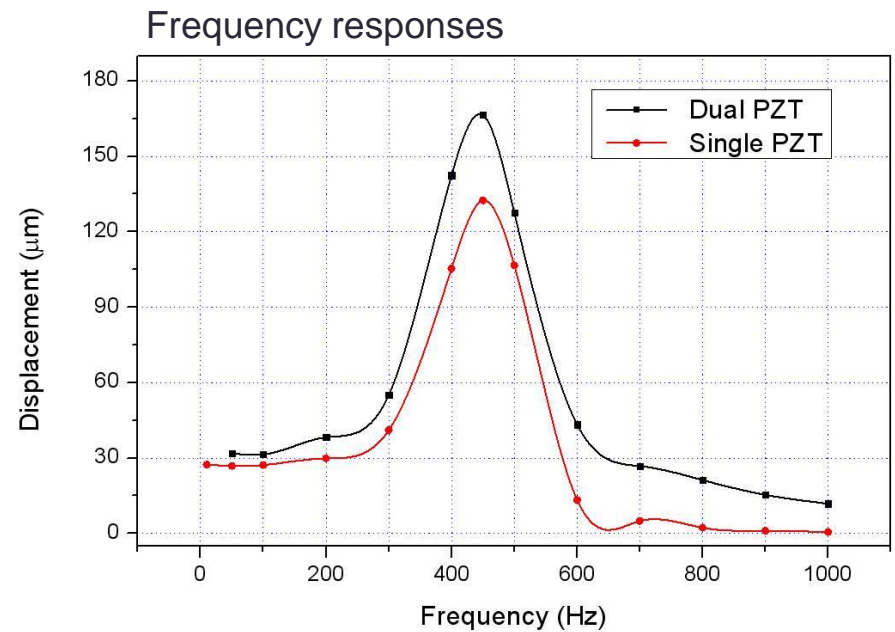
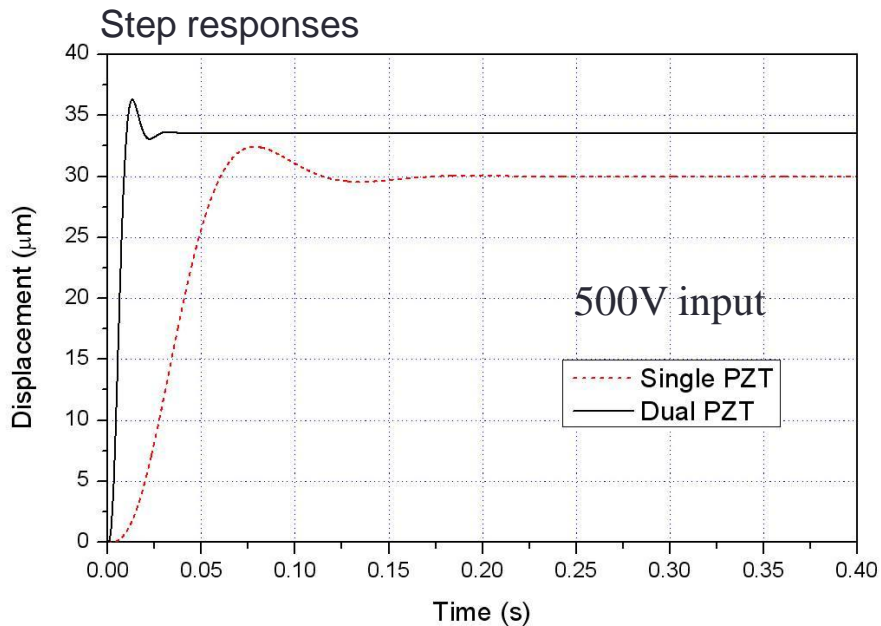
Specifications of piezoelectric actuator

PZT P-010.40 (PI)	Displacement	Blocking force	Stiffness	Capacitance
	60 μm	2200 N	38 N/ μm	260 nF

Comparison of response characteristics between single and dual PZT actuators

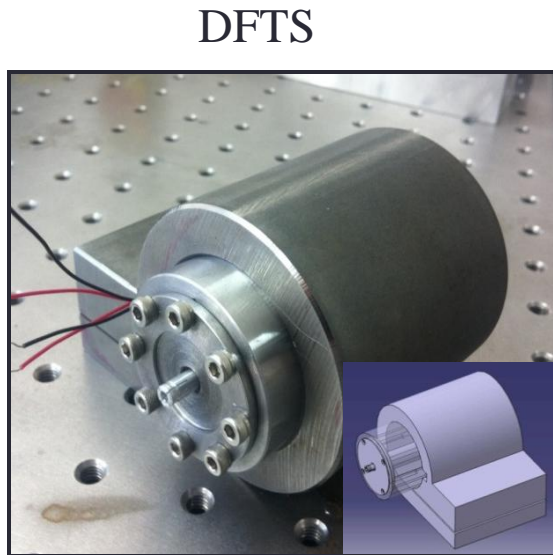
✓ Frequency response and step response

DFTS: FTS actuated by dual PZT; SFTS: FTS actuated by single PZT

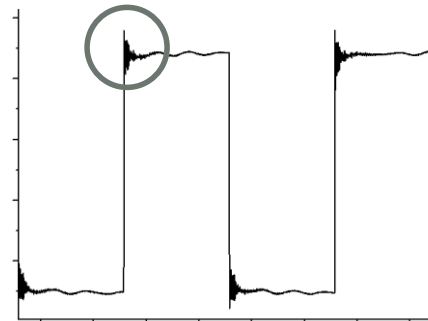


Response characteristics in new DFTS designed for roll machining

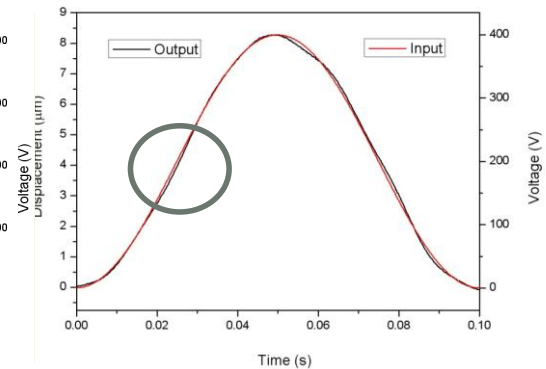
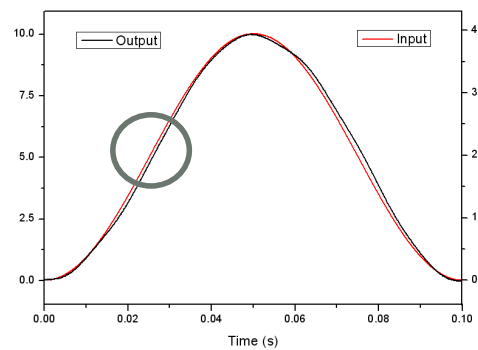
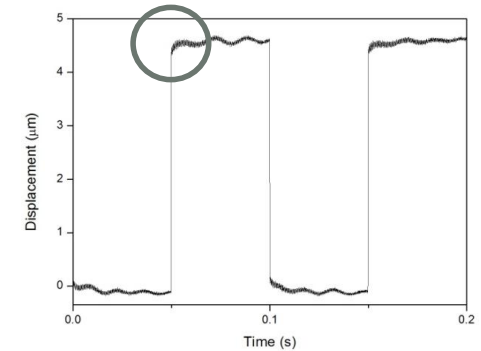
- ✓ Comparing two types of FTS actuated by single and dual PZT



SFTS



DFTS

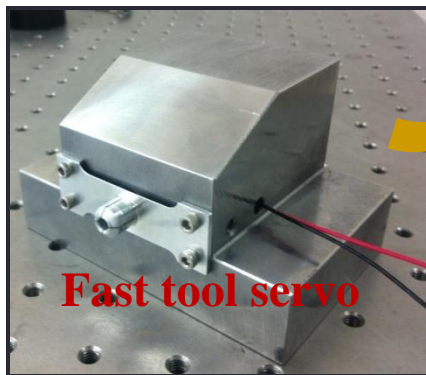
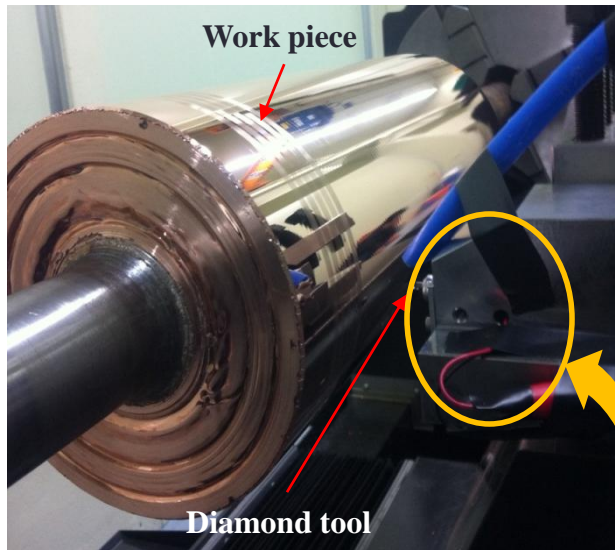


Output stroke of FTS (10 Hz)

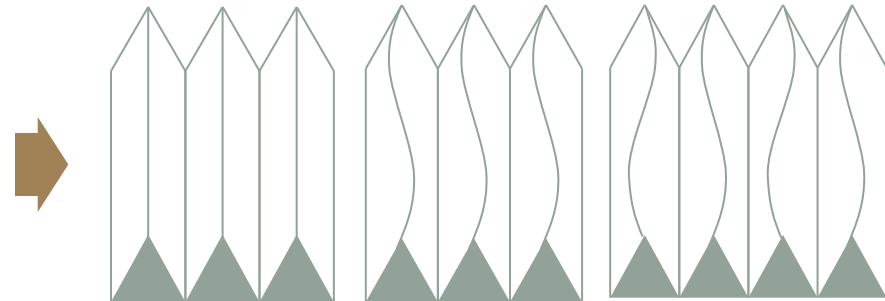
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Machining test of mold roll using FTS



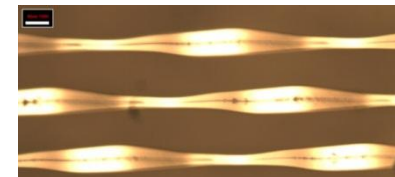
Experimental Setup



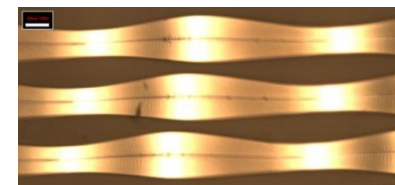
Cutting conditions

Feed rate 100 $\mu\text{m}/\text{rev}$	$f = 1000 \text{ Hz}$ $n = 48 \text{ rpm}$	Wave length(L) $440 \mu\text{m}$
	$f = 1500 \text{ Hz}$ $n = 72 \text{ rpm}$	
	$f = 2000 \text{ Hz}$ $n = 96 \text{ rpm}$	
Feed rate 20 $\mu\text{m}/\text{rev}$	$f = 1000 \text{ Hz}$ $n = 48 \text{ rpm}$	
	$f = 1500 \text{ Hz}$ $n = 72 \text{ rpm}$	
	$f = 2000 \text{ Hz}$ $n = 96 \text{ rpm}$	

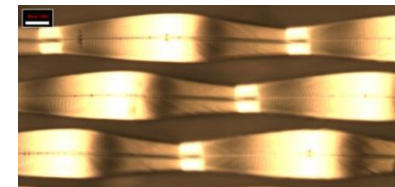
1000Hz, 48 rpm



1500Hz, 72 rpm



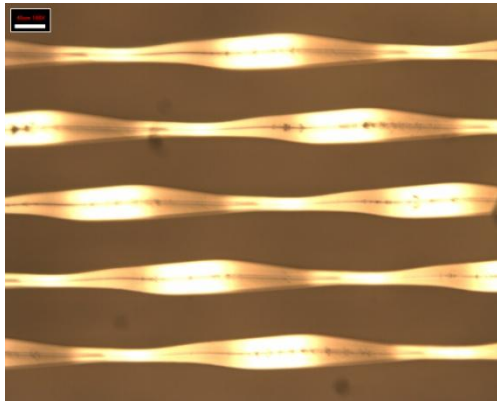
2000Hz, 96 rpm



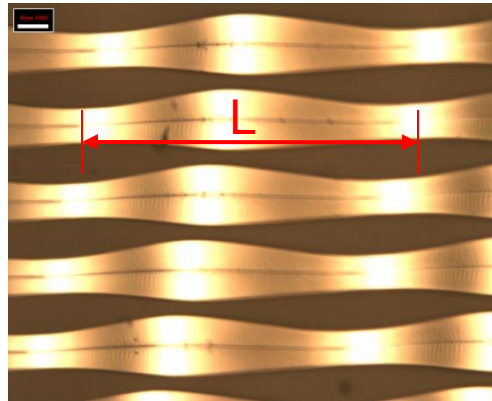
Results of micro patterning on mold roll surfaces(Type A)

✓ Patterns machined by various cutting conditions

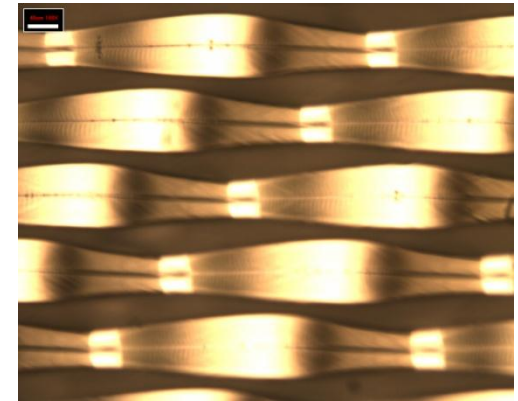
1000Hz, 48 rpm



1500Hz, 72 rpm

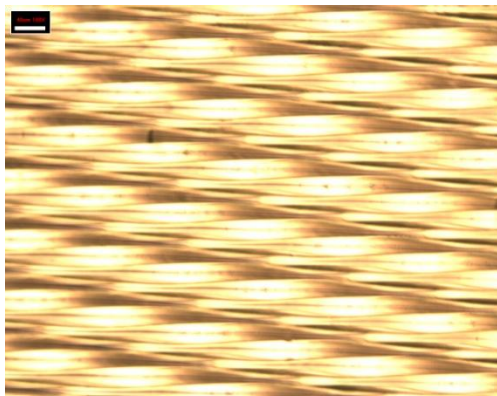


2000Hz, 96 rpm

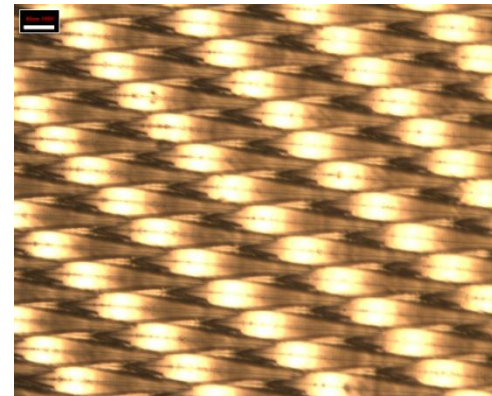


Feed rate
100μm/rev

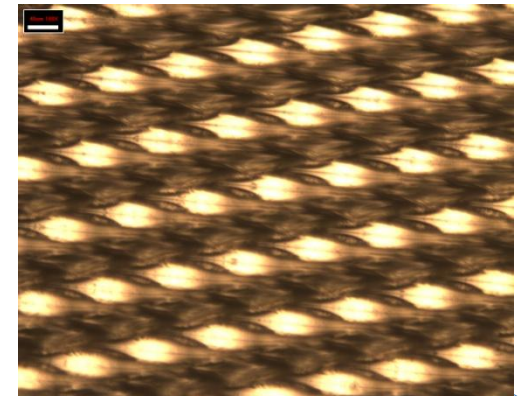
1000Hz, 48 rpm



1500Hz, 72 rpm



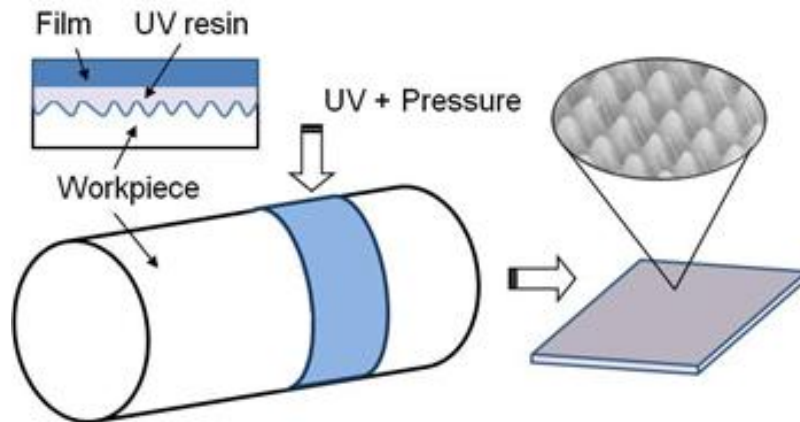
2000Hz, 96 rpm



Feed rate
20μm/rev

Evaluating of pattern profiles machined on mold roll surfaces

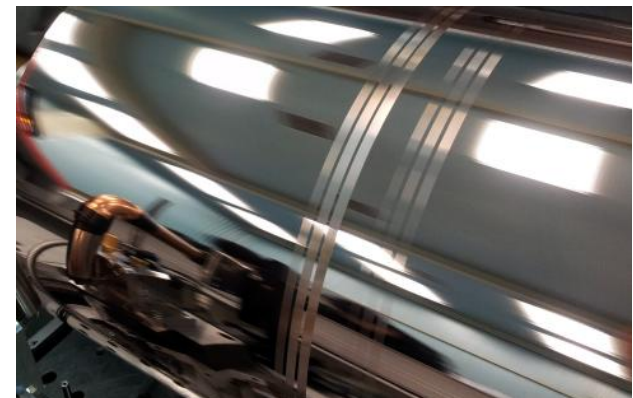
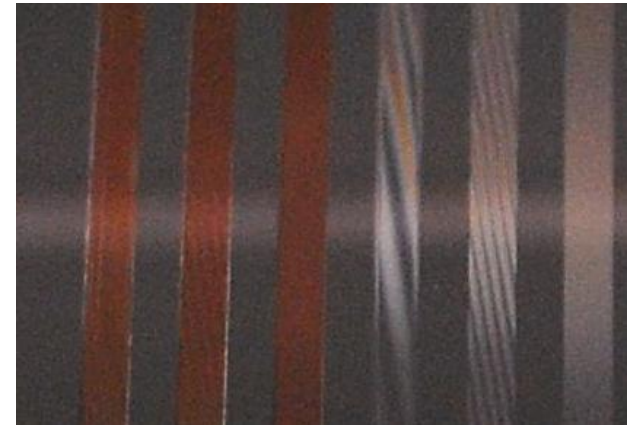
✓ UV-casting process



Conditions of UV-casting

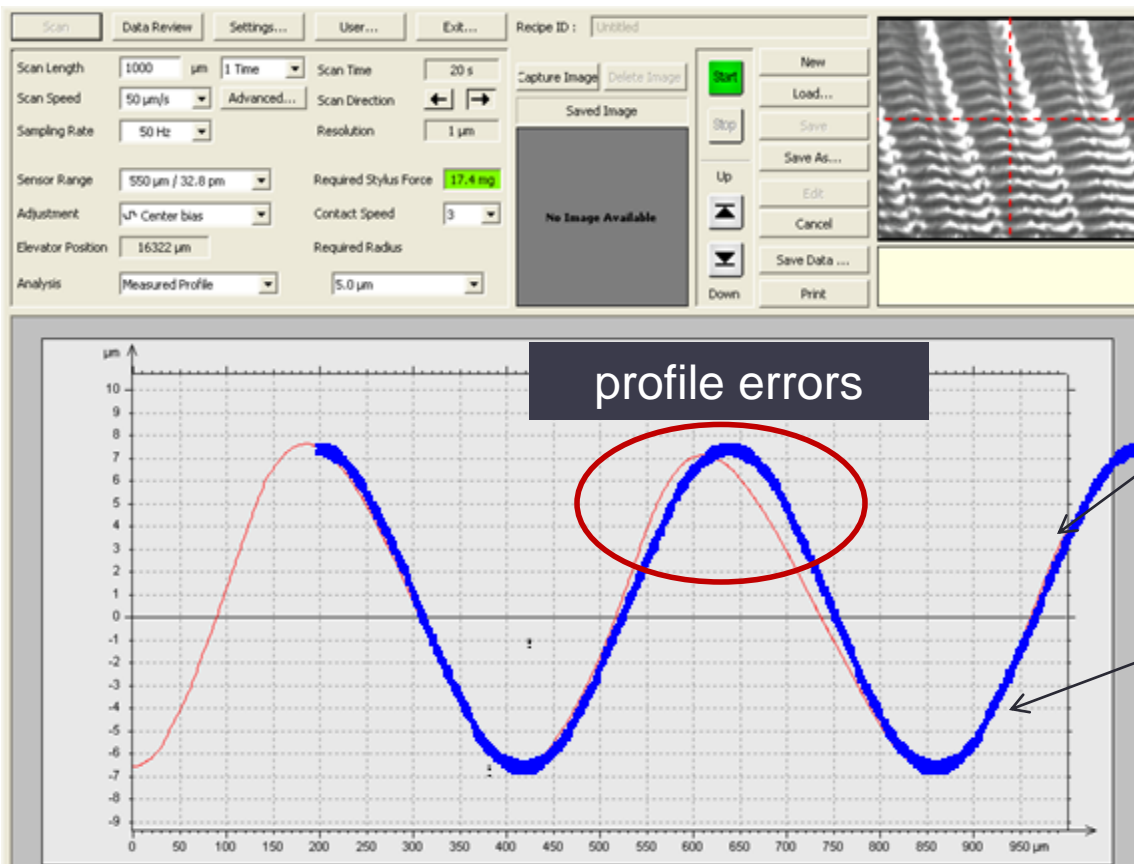
Resin	UV resin
Film	290 x 210 mm Thickness: 100 μm
Time (UV light applied)	5 min

Patterned film by imprinting process



Pattern profiles transferred by UV film casting

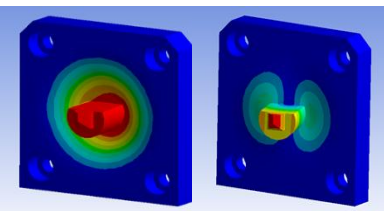
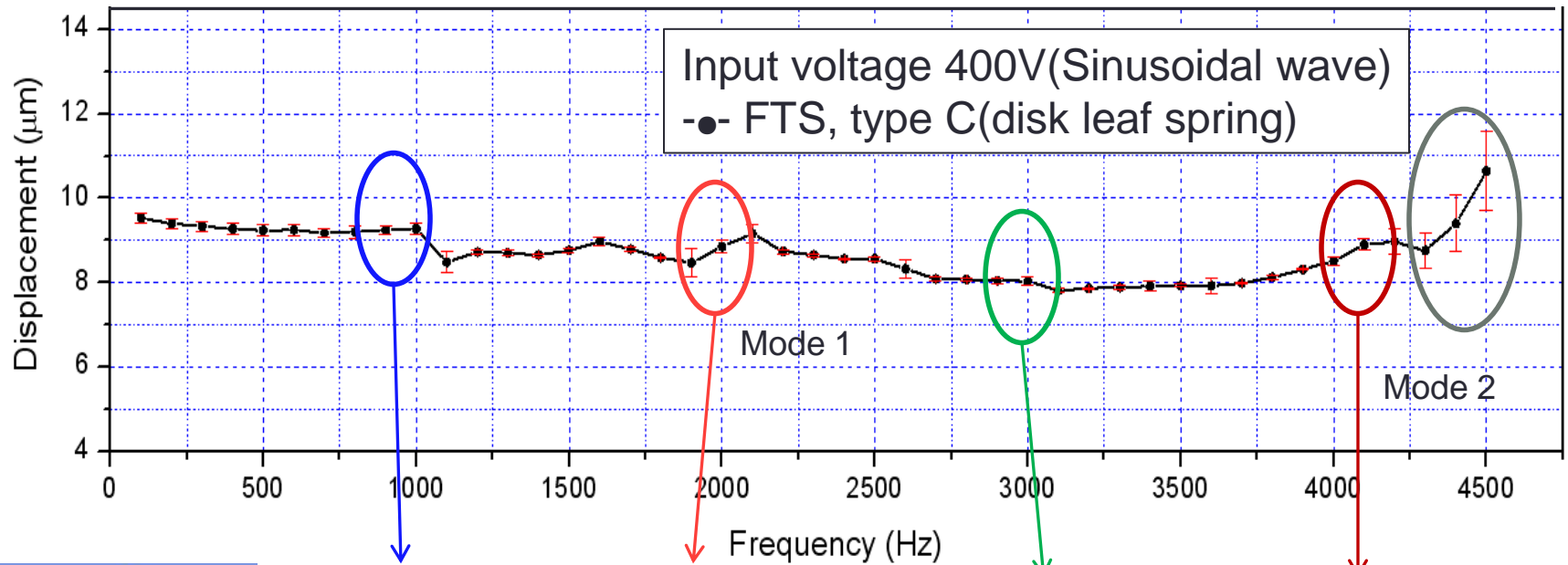
- Input Voltage 500V, FTS 1500 Hz, spindle speed 72rpm, feed rate 100 μ m/ rev
Wavelength 440 μ m, Depth of cut 14 μ m



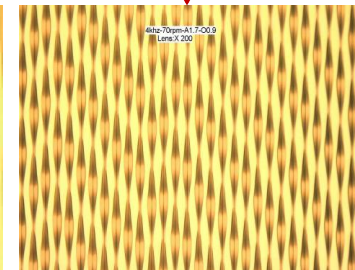
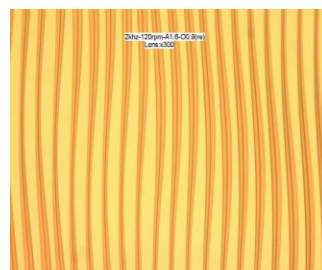
Measured profile

Sine wave
(given input profile)

Evaluating machined patterns at each actuating frequency



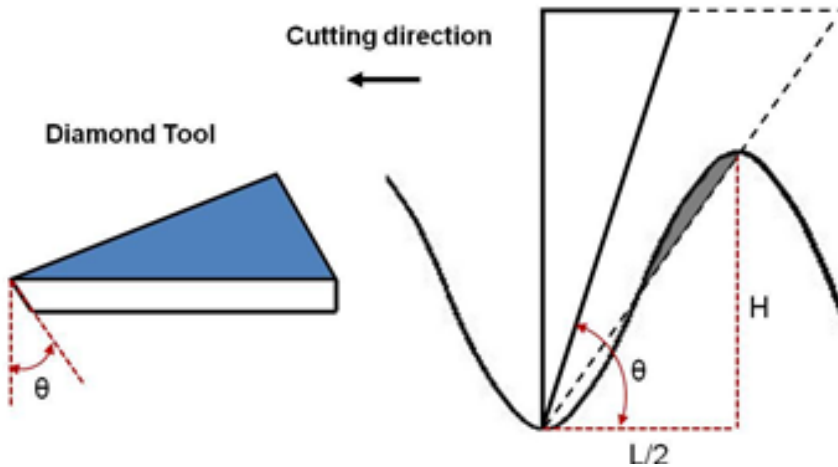
Mode1 Mode2



✓ Irregular patterns at near 2kHz and 4kHz due to uncontrollable vibration.

Deformed profiles caused by conditions of FTS cutting

✓ Selection of tool clearance angle



- $\theta > \theta_c$, $\theta_c = \arctan(2H/L)$

Θ : the clearance angle of tool

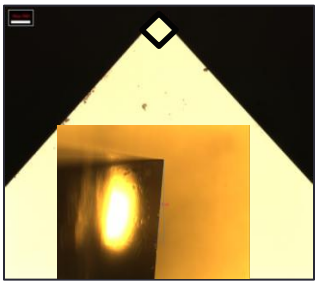
Θ_c : the tangential angle of input wave

H: the amplitude of profile ; depth of cut

L: the wavelength of profile

❖ Ex.) Height, $H = 5\mu\text{m}$, Wavelength, $L = 100\mu\text{m}$.
Clearance angle of tool, $\theta \geq 6$ degrees.

Specifications of diamond tool

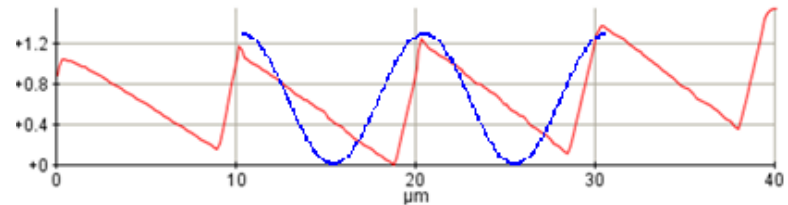


Microscope imagine

Tool material	Diamond
Clearance angle	5 degrees
Nose angle	90 degrees

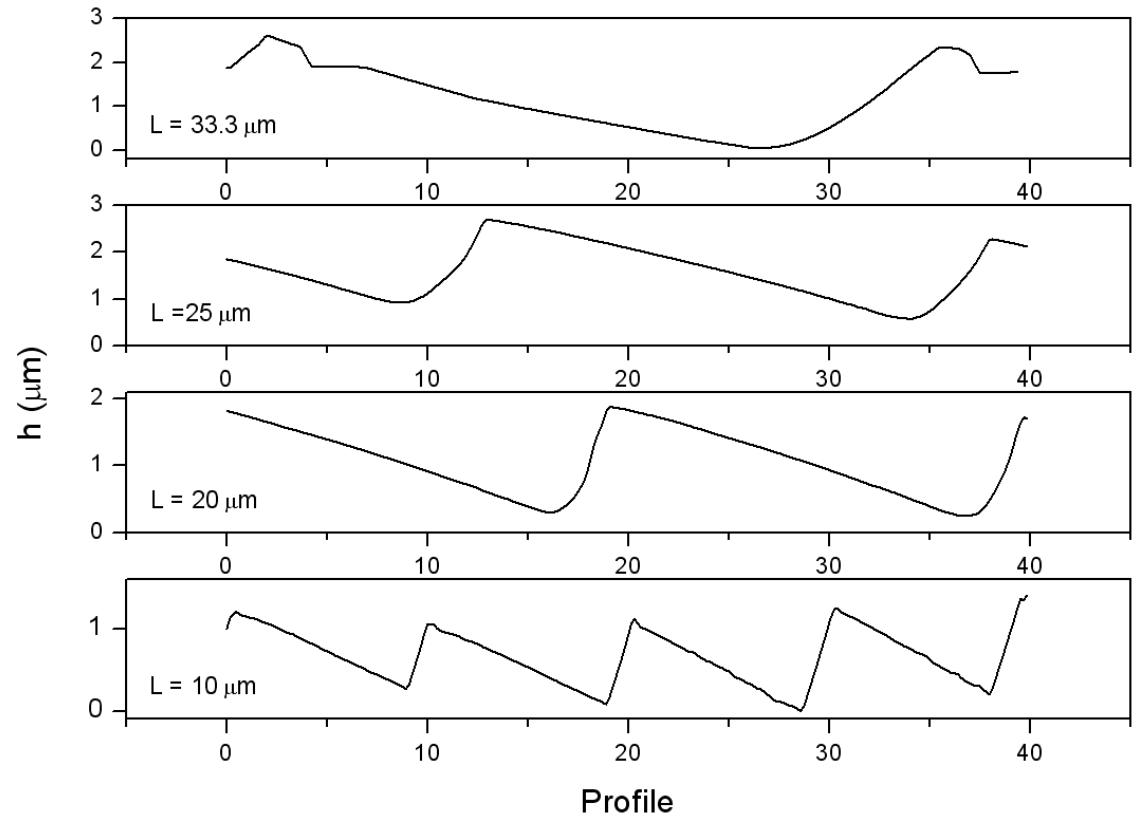
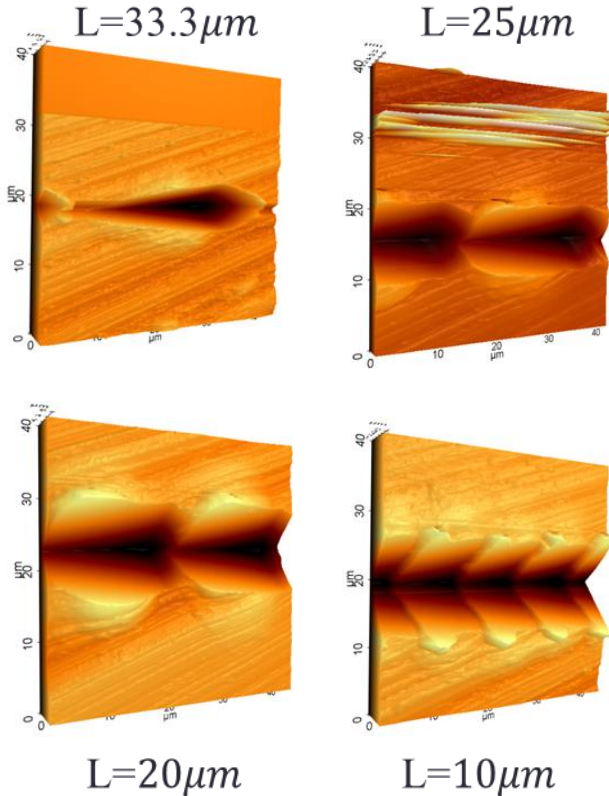
Statistics

Line	Min(μm)	Max(μm)	Mid(μm)	Mean(μm)	Ra(μm)	Rz(μm)
Red	0.003	1.553	0.778	0.700	0.292	0.059



Machining test to investigate deformed profiles

✓ Deformed profiles according to the variation of wavelengths



Bur formation due to plastic deformation of machined structure

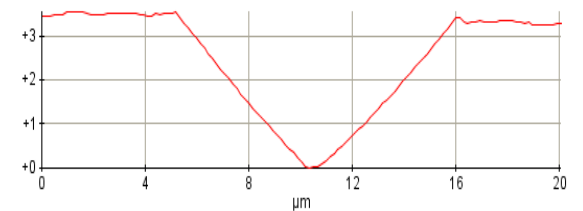
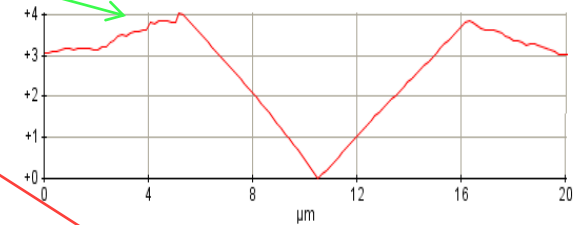
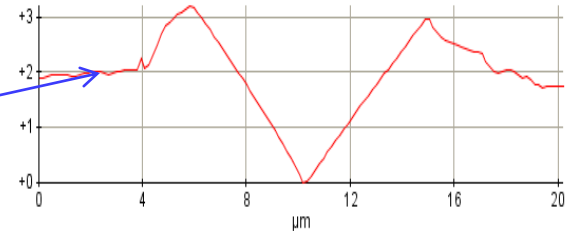
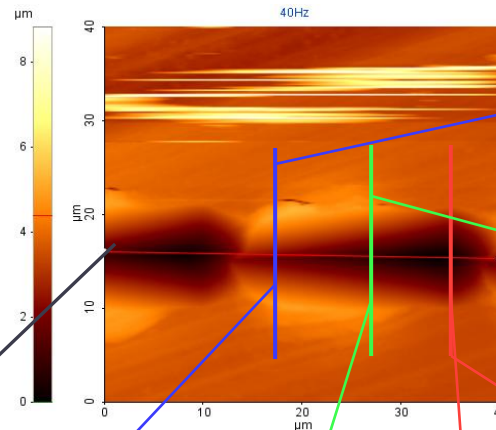
<Cutting conditions>

FTS: 100Hz

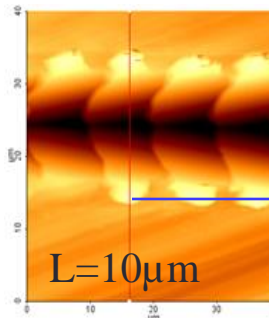
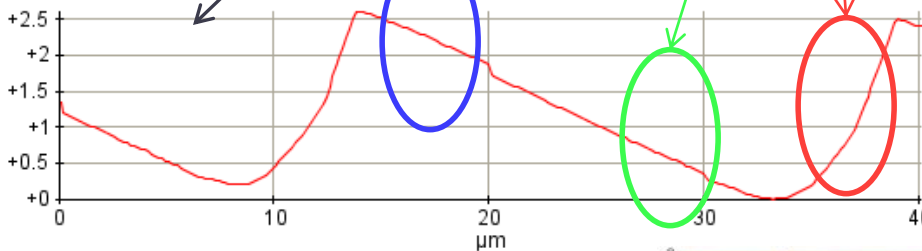
Wave length, $L=25\mu\text{m}$

Clearance angle of tool, $\theta=5$ degrees

Depth of cut, $H=5\mu\text{m}$

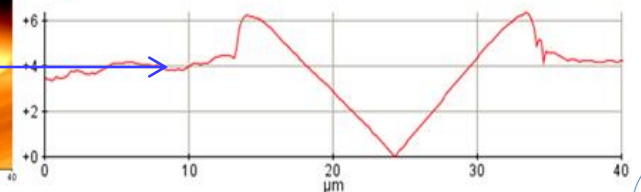


Longitudinal profile



Statistics

Line	Min(μm)	Max(μm)	Mid(μm)	Mean(μm)	Ra(μm)	Rz(μm)
Red	0.311	6.713	3.512	4.125	1.057	-0.594



- ✓ Machining region : without bur
- Plastic deform region : bur formation

Conclusions

- A prototype of FTS system with PZT actuator was developed for diamond turning applications.
 - Experiments to describe the hysteresis behaviors of FTS were performed.
 - The hysteresis nonlinearity of FTS must be compensated by feed back control in low bandwidth of FTS.
 - DFTS with dual PZT actuators showed better tracking performances and longer travel range than SFTS with single PZT actuator.
- Microstructures on mold roll surfaces were manufactured in diamond turning using FTS system.
 - It is necessary to select suitable tool shape according to given cutting conditions(especially, clearance angle of tool) in order to fabricate desired profiles.

Thank you for your attention !!!

